

The International Symposium on
Optical Science and Technology

**Noise performance comparison of
ICCD with CCD and EMCCD cameras**

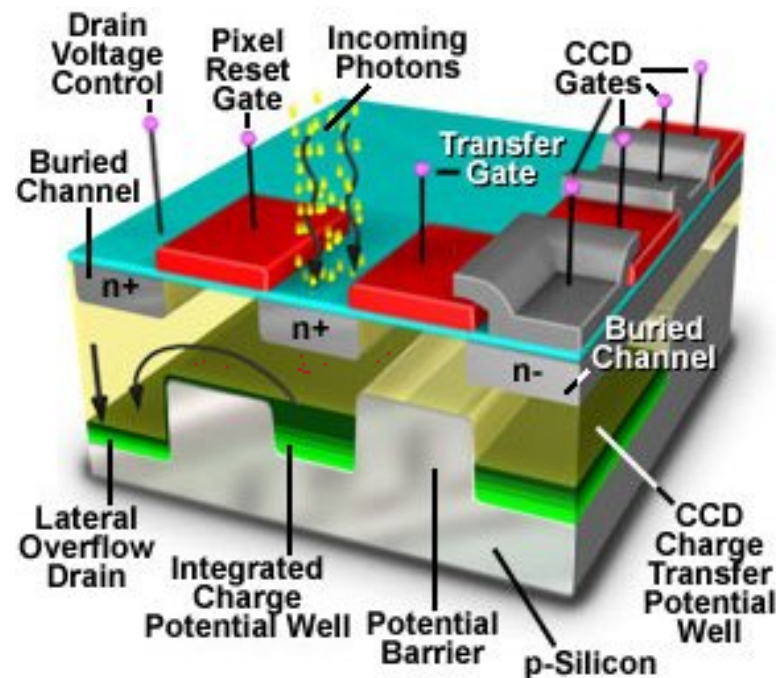
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Topics

- **Introduction - 3 LLL sensing concepts**
 - CCD
 - ICCD
 - EMCCD
- **Noise sources**
 - Shot noise
 - Dark current noise
 - Readout noise
- **Signal-to-noise ratio**
 - Single frame operation
 - Long integration time versus frame adding
- **Discussion of the simulation results**
- **Conclusions**

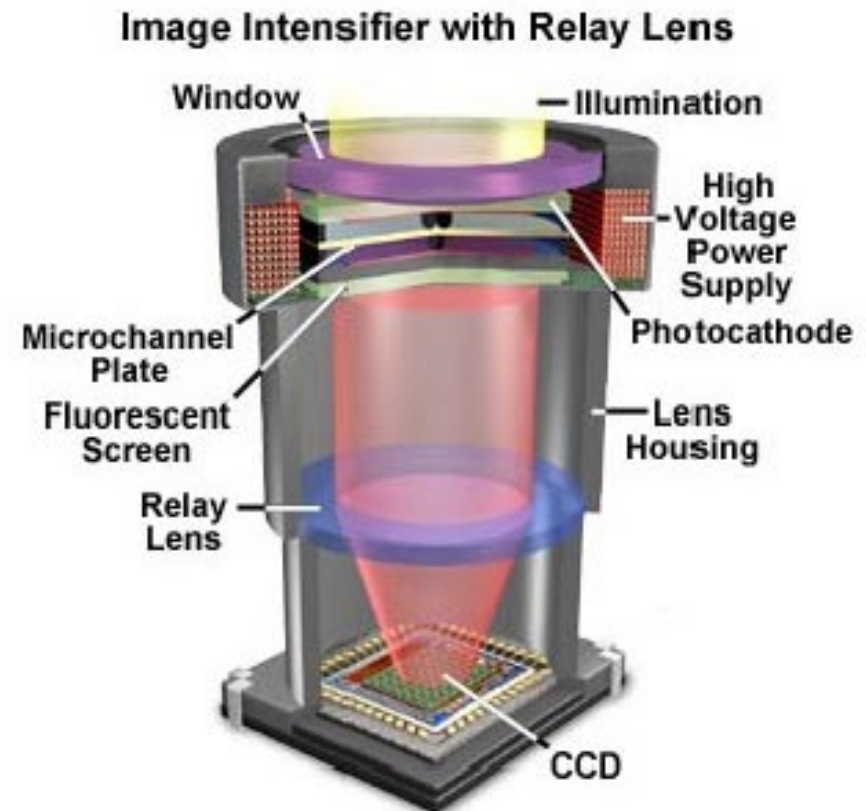
CCD (Charge-Coupled Device)



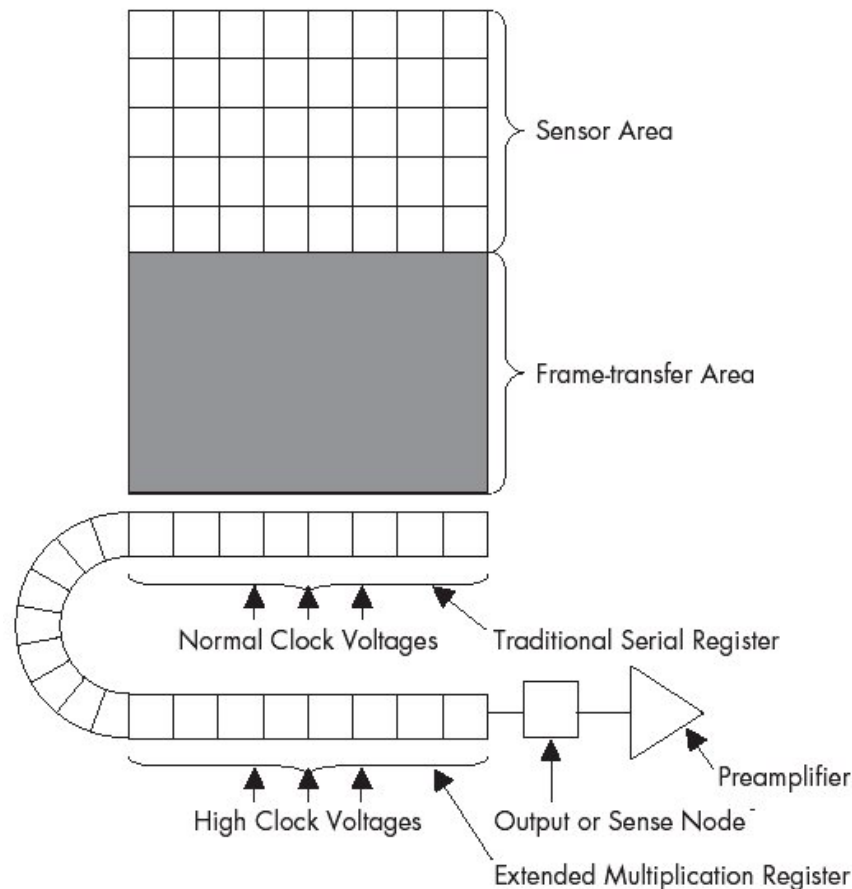
- CCD = array of photodiodes (light-sensitive pixels).
- **Generation** (high Q.E. η , $1e^-$ per photon) and **storage** of electrons when exposed to light.
- Read-out of the charge by changing the electrical bias of an adjacent pixel.
- Charge to voltage conversion, digitization to numerical value by external circuitry.

ICCD (Intensified CCD)

- Photocathode: Generation (low Q.E. η , $1e^-$ per $h\nu$) of photoelectrons.
- Microchannel plate (MCP): multiplication (G_{MCP}) of electrons.
- Phosphor screen: conversion (G_{screen}) of electrons back into highly increased ($\times 10^4$ - 10^6) number of photons.
- High numerical aperture lens-coupling for superior distortion free image quality.
- CCD: conversion of the very high number of photons to charge, readout and digitization.



EMCCD (Electron Multiplying CCD)



- Generation and storage of electrons (high Q.E. η , $1e^-$ per photon), equivalent to CCD.
- Amplification by impact ionization in the gain register.
- Charge to voltage conversion, digitization equivalent to CCD.

Noise sources [1]

All signals and noises are calculated in equivalent number of electrons at system output.

- Shot noise N_{shot} [e⁻/pixel]

$$N_{\text{shot}} = G \times F \times \sqrt{\eta \phi_p \tau}$$

G: multiplication gain

F: noise factor of gain

η : quantum efficiency

ϕ_p : mean incident photon flux per pixel

τ : integration time [s]

Noise sources [2]

- Dark current and its noise N_{dc} [e⁻/pixel]

$$N_{dc} = \left[2.55 \cdot 10^{15} N_{dc0} \tau \cdot d_{pix}^2 T^{\frac{3}{2}} e^{\left(\frac{-E_g}{2kT}\right)} \right]^{\frac{1}{2}}$$

N_{dc0} : dark current at room temperature [nA/cm²]

d_{pix} : pixel size [cm]

T: operating temperature [K]

E_g : bandgap energy in eV

k: Boltzmann's constant

($8.62 \cdot 10^{-5}$ eV/K)

Noise sources [3]

- Read-out noise N_r :
 - generated through charge transfers across the CCD.
readout amplifier reset, “any other” electronic noises
 - Strongly pixel clock (frame rate) and slightly temperature dependent.
 - independent of integration time.
 - for EMCCDs:

$$N_r = \left[N_{r0}^2 + (G \times N_{ct})^2 \right]^{1/2}$$

where N_{ct} is the charge transfer noise that is multiplied in the gain register and N_{r0} is all other non-multiplied readout noises.

Noise sources

- Total noise N_{tot} :

$$N_{tot} = \left(N_{shot}^2 + N_{dc}^2 + N_r^2 \right)^{1/2}$$

Signal-to-noise ratio [1]

- Single frame operation

$$SNR_{unit} = \frac{G\eta\phi_p\tau}{(N_{shot}^2 + N_{dc}^2 + N_r^2)^{1/2}}$$

- Shot-noise-limited operation if N_r and $N_{dc} \ll N_{shot}$:
 - high Φ_p ,
 - high G ,
 - or N_r and N_{dc} extremely small.

Signal-to-noise ratio [2]

- Long time integration (traditional approach):

$$SNR_{long} = \frac{n_l G \eta \phi_p \tau}{\left[n_l (N_{shot}^2 + N_{dc}^2) + N_r^2 \right]^{1/2}} = \sqrt{n_l} \frac{G \eta \phi_p \tau}{\left[N_{shot}^2 + N_{dc}^2 + (N_r^2 / n_l) \right]^{1/2}}$$

where n_l is the factor by which the integration time τ is increased.

Parameters of the simulation

■ **CCD:**

- $\eta=50\%$, front-illuminated
- $G=F=1$
- $N_r=25e^-$ (5MHz) or $5e^-$ (1MHz)

■ **ICCD:**

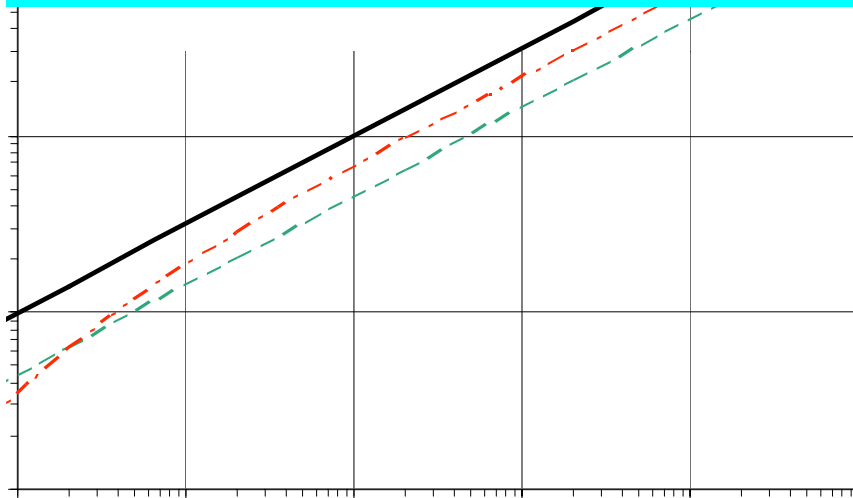
- $\eta=50\%$
- $F=1.6$
- $G=500$
- $N_r=25e^-$

■ **EMCCD:**

- $\eta=50\%$ (FI) or 90% (BI)
- $F=1.4$
- $G=500$
- $N_{r0}=25e^-$
- $N_{ct}=2.2e^-$ (31kHz) or $5.4e^-$ (1MHz)

- $\tau=20$ ms
- $N_{dc0}=0.1$ or $3nA/cm^2$ @ 300K

Short frame mode



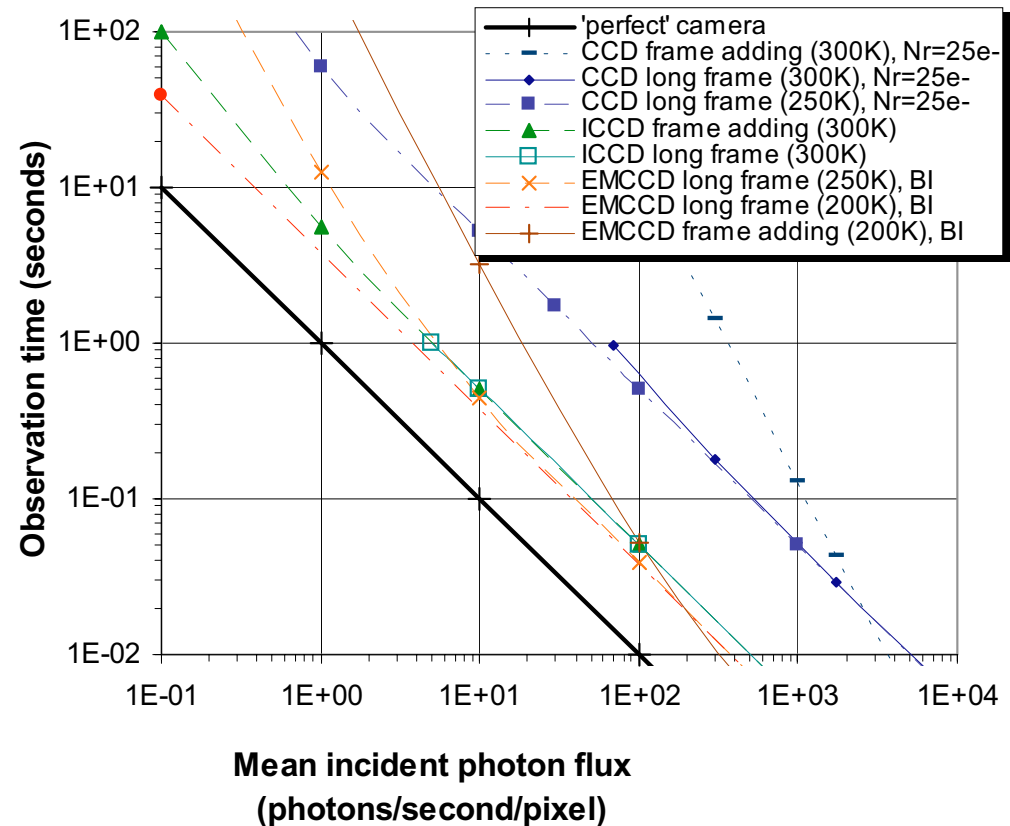
Simulation of extended integration time

low to very low Φ_p , low camera noise

- **CCD:**
 - Better SNR with long frame.
- **EMCCD:**
 - Clear influence of cooling in low light conditions,
 - frame adding not as effective as for ICCD.
- **ICCD:**
 - Same results with frame adding or long frame,
 - cooling not required.

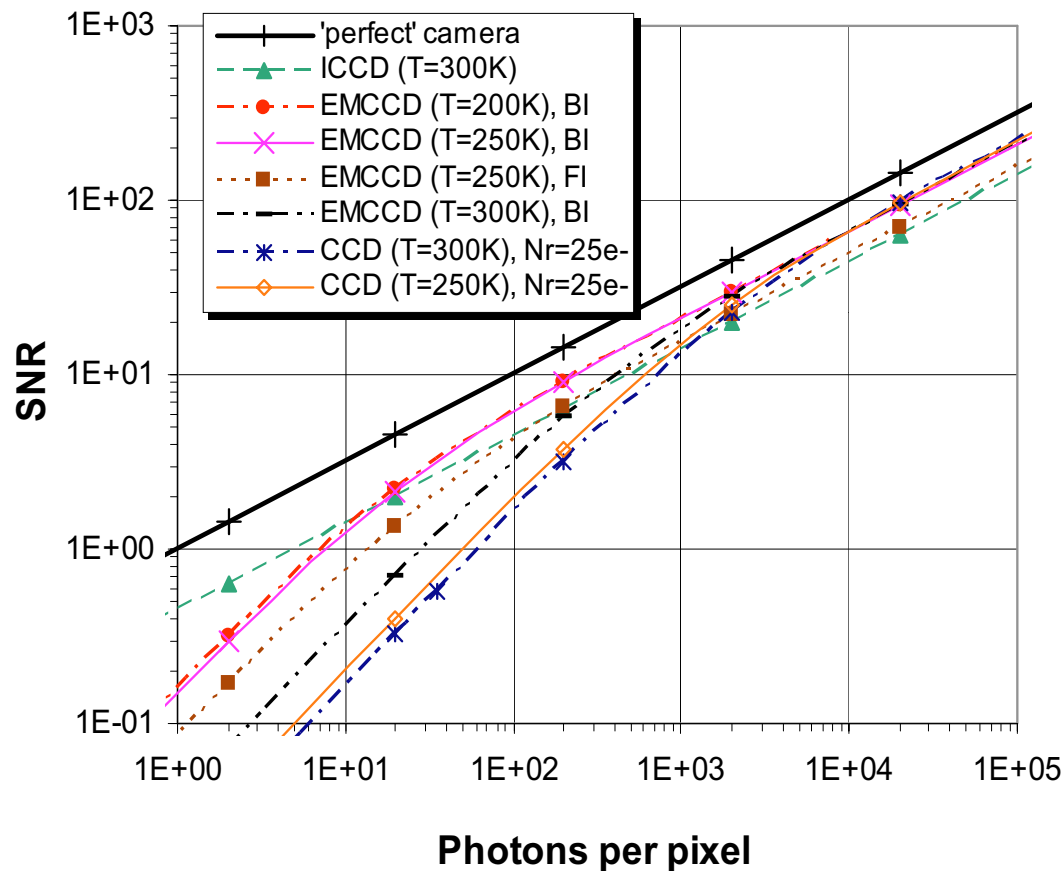
Parameters:

- $\tau=20\text{ms}$
- $N_{\text{dc0}}=0.1\text{nA/cm}^2$
- $N_{\text{ct}}=2.2e^-$



Simulation of single short frame mode

high to medium Φ_p , high camera noise, realistic operating conditions



- **CCD:**
 - Negligible temperature influence at 5MHz readout rate.
- **EMCCD:**
 - Still a decrease of the SNR in LLL,
 - Slightly superior to CCD at room temperature,
 - SNR improvement for lower temperatures,
 - BI: high QE, slight temperature dependence, readout dominated.
- **ICCD:**
 - Still in shot-noise-limited operation, unchanged.

Parameters:

- $\tau=20\text{ms}$
- $N_{\text{dc}0}=3\text{nA/cm}^2$
- $N_{\text{ct}}=5.4e^-$

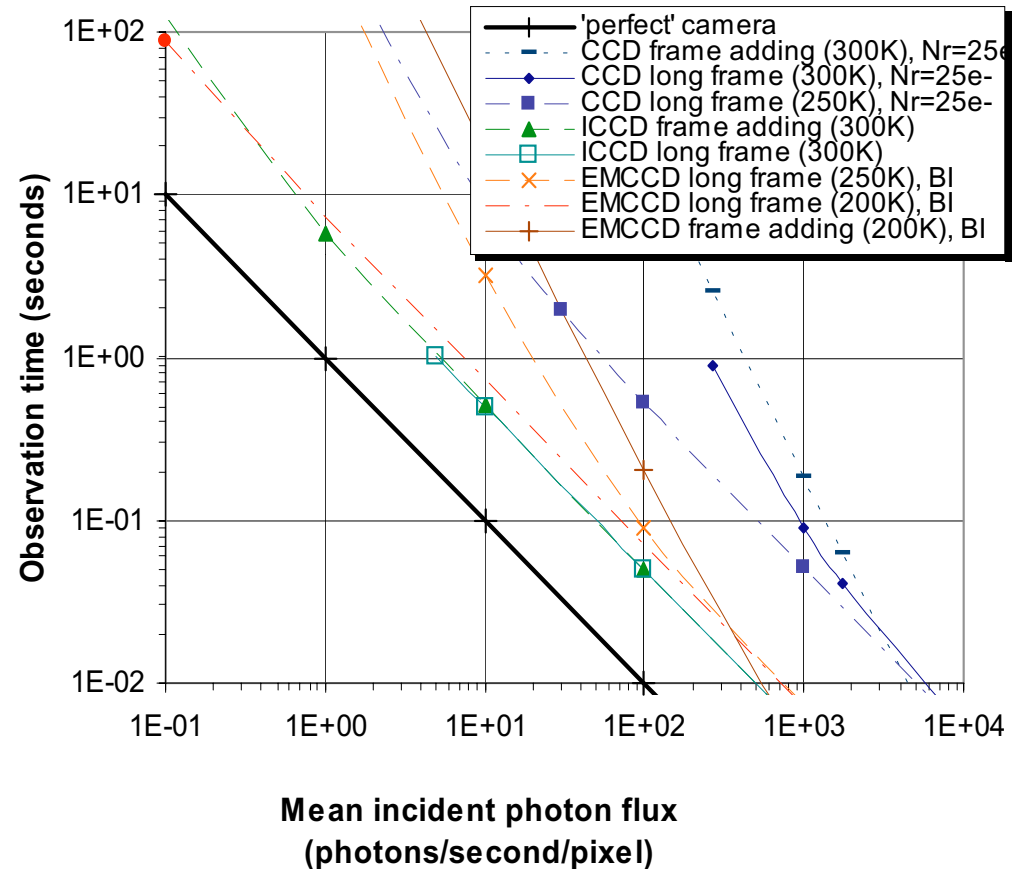
Simulation of extended integration time

low to very low Φ_p , high camera noise, realistic operating conditions

- **CCD:**
 - Long frame better than frame adding,
 - Frame adding: significant sensitivity increase without additional hardware.
- **ICCD:**
 - No influence of noises, better than EMCCD over a wide range.
- **EMCCD:**
 - Better than ICCD only at extremely low light levels (int. time \geq 1min.)

Parameters:

- $\tau=20\text{ms}$
- $N_{dc0}=3\text{nA/cm}^2$
- $N_{ct}=5.4e^-$



Conclusions

- Best SNR provided by CCD at high light levels, operating range extended to low light levels through slow scan and cooling.
- Need for strong cooling of EMCCD sensors to eliminate dark current.
- Need for very low frame rates operation for EMCCDs in order to minimize charge transfer noise.
- **No cooling, no slow scan required for the CCD sensor of an ICCD system.**